

Localized Fault Recovery for Nested Fork-Join Programs



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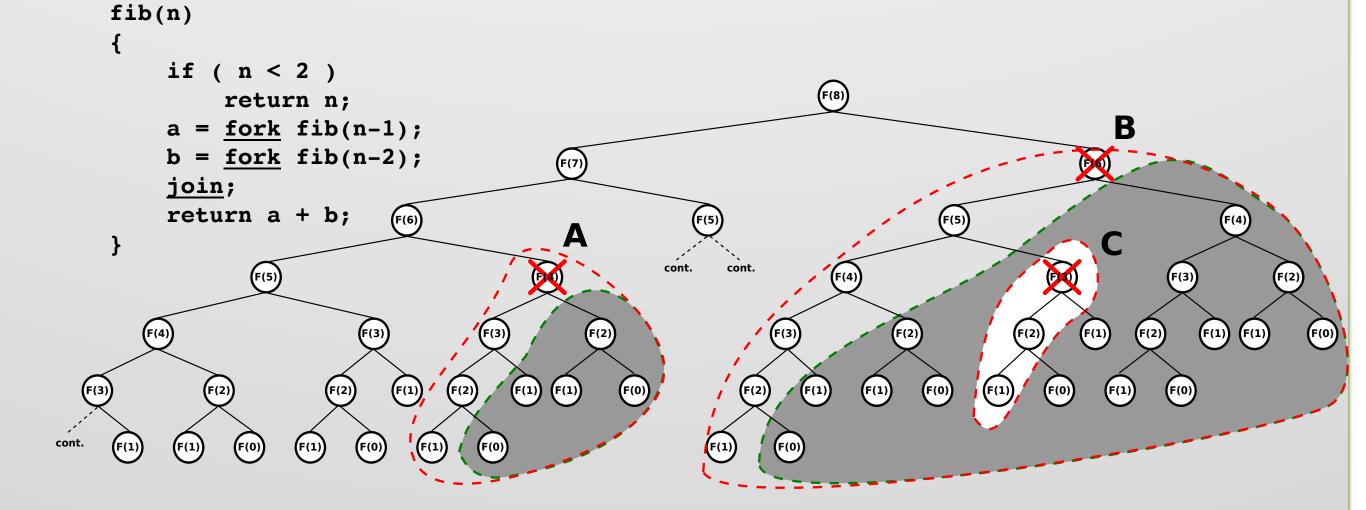
Introduction

- High performance computers are increasingly susceptible to errors
- Periodic checkpointing is widely used approach to fault tolerance, but
- recovery cost can be proportional to system size
- it introduces large performance overhead
- We consider the design of fault tolerance mechanisms in the presence of fail-stop failures for
- nested fork-join programs,
- executed on distributed memory machines,
- load balancing provided by work stealing

Nested fork-join models provide an opportunity to perform localizated fault recovery

Problem Statement and Objectives

- Reducing the amount of re-executed work in the presence of failures
- Guaranteeing forward progress even during fault recovery
- Ensuring correct interleaving of remote operations and error notifications
- Efficiently handling nested recovery, concurrent recovery, and failureduring-recovery scenarios



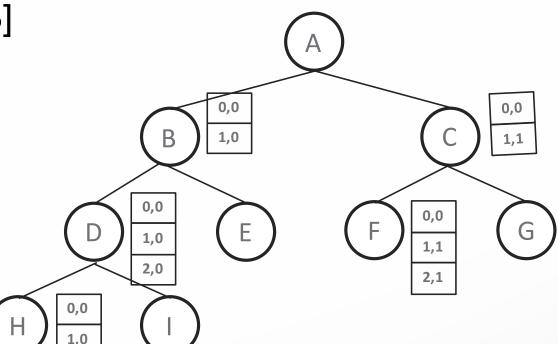
Our Proposal: ForkJoinFT

- A modified distributed-memory algorithm that incorporates efficient fault recovery
- ForkJoinFT executes all and only lost work due to a fault, it needs to:
 - 1. track the relationship between the subcomputations performed by different threads
- 2. reconstruct the relationship among live processes that have pending interactions with the failed node
- 3. re-execute all and only lost subcomputations without interfering with the normal task execution

Gokcen Kestor, Sriram Krishnamoorthy, Wenjing Ma, "Localized Fault Recovery for Nested Fork-Join Programs", *IEEE International Parallel and Distributed Processing Symposium IPDPS 2017*, pp. 397-408, May 2017, Orlando (FL).

Tracking Global Computation

- We extended steal tree algorithm [PLDI'13] to retain only the *live* portion of subcomputations:
- each steal operation is identified with a unique ID (victim rank, working phase, level, and step)
- at every steal operation, the thief gets its victim steal path and adds the current steal operation
- all the preceded steals (Stolen Step)
 from a given victim in the same working
 phase are recorded



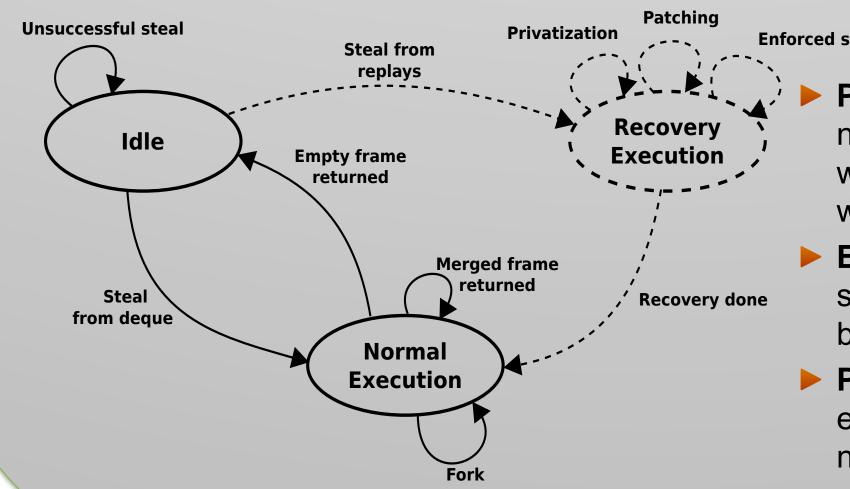
Recovering Global Computation

- Failure notifications are assumed to be sent to the server threads
- Upon a failure notification, each server thread independently initiates recovery:
- Identifies pending subcomputations stolen by the failed worker
- marks the victim of the failed worker as a recovery node
- requests steal tree paths that include the failed worker from all workers
- collects all steal tree paths and construct a replay tree
 - the root of the replay tree is the subcomputation stolen by the failed worker
- collection is a distributed binary-tree-based reduction
- makes the replay tree and its root task ready to be stolen

ForkJoinFT re-executes only lost subcomputations

Scheduling Re-Execution

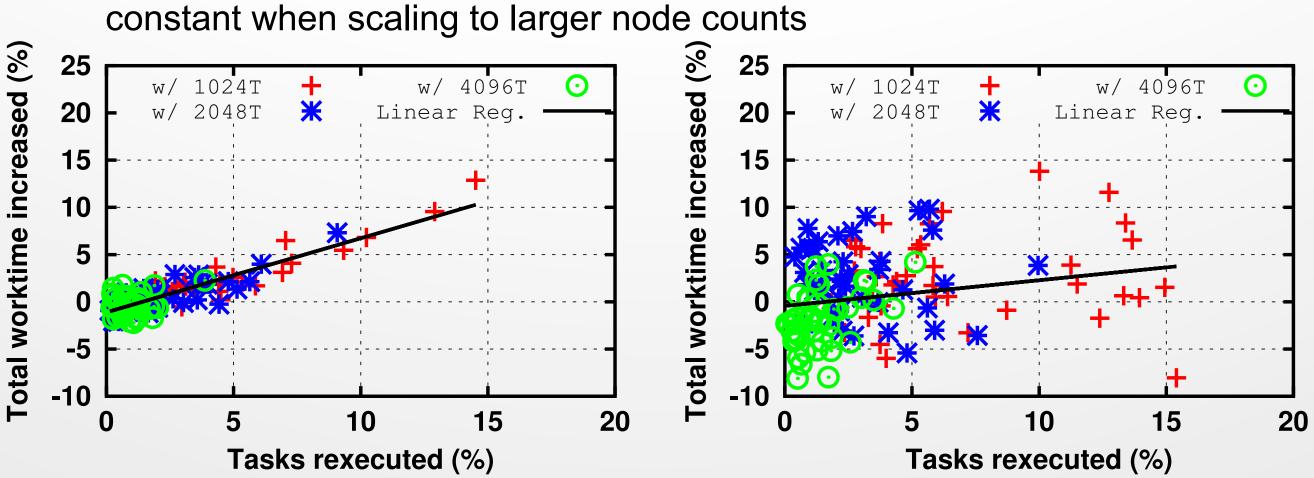
- When a thief steals work to be re-executed:
- its victim determines the task's frontier
- task's frontier is the failed worker's list of alive children
- the thief assumes ownership of the root task of replay tree
 - thieves of this subcomputation will return their results to new owner, rather than the failed worker



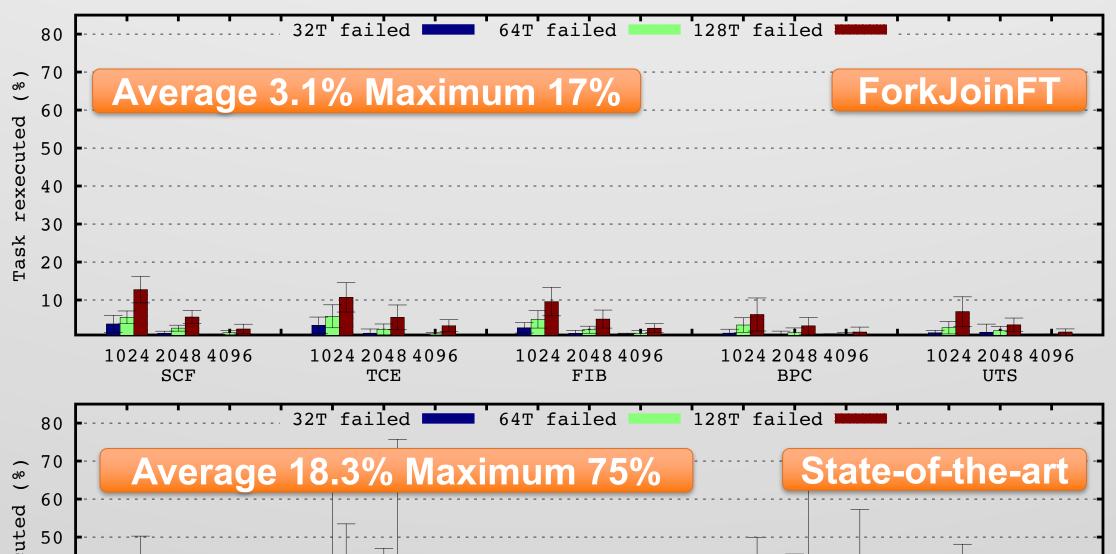
- Privatization: spawned task is not stolen in the failed execution, will be executed by the current worker
- ► Enforced steal: spawned task is stolen in the failed execution, will be donated to other thieves
- Patching: spawned task already exists in another live worker, no need to be executed

| 1.2 | 32 nodes | 64 nodes | 128 nodes | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.15 | 1.

- Negligible overhead and does not increase with core count
- Space overhead per thread is generally a few KB and remains roughly constant when scaling to larger node counts



- The increase of total work time is generally less than 15%
- A regression analysis (OLS) models the relation between the number of re-executed tasks and the increase in work time reveals (sub) linear relationships



Conclusions

- We presented an approach to localized fault recovery specific to nested fork-joined programs executed on distributed-memory systems
- Our fault tolerance approach:
- introduces negligible overhead of in the absence of faults, within the execution time variation
- re-executes all and only lost work due to faults

1024 2048 4096

- significantly decreases the amount of work re-executed as compared to alternative strategies
- presents a recovery overhead roughly proportional to the amount of lost work